

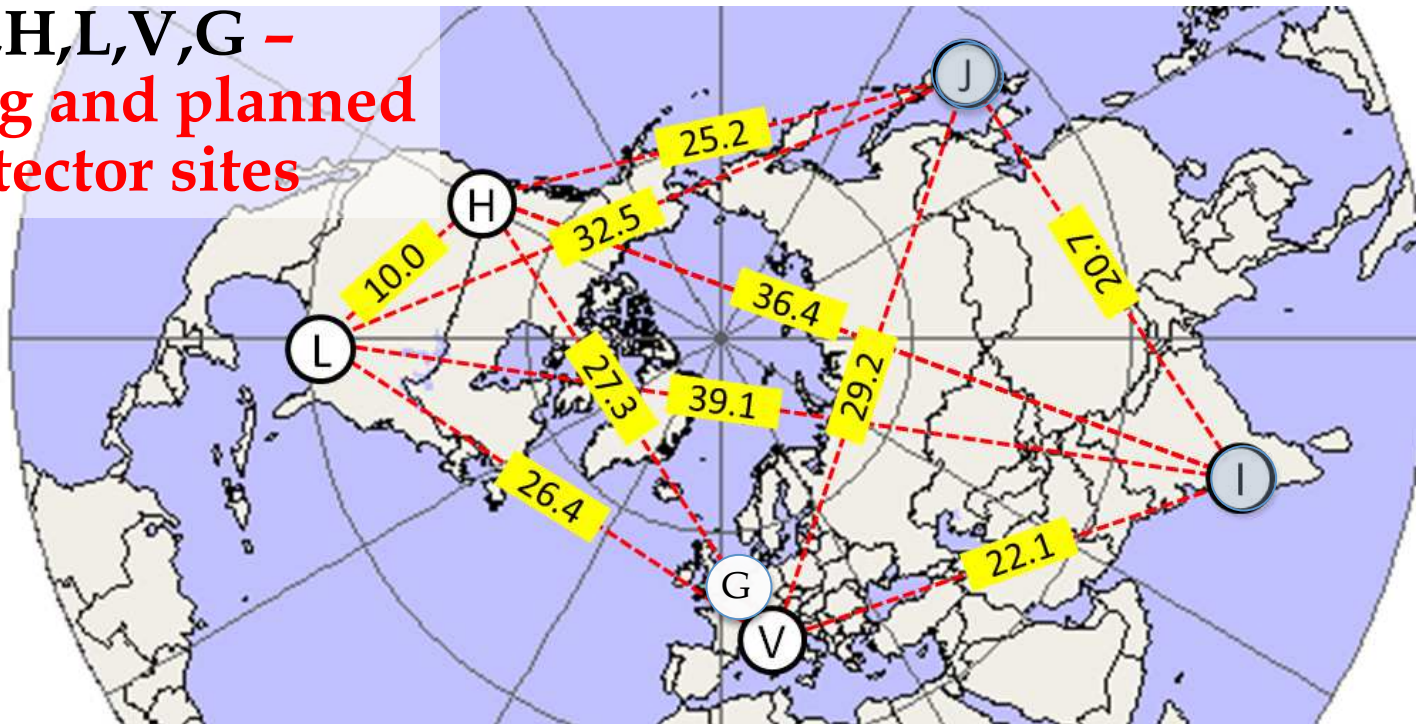


Optimal detector networks for multi-messenger astronomy with transient gravitational waves

(impact of site topology)

S.Klimenko (University of Florida)
and **G.Vedovato** (INFN, Padova)

I,J,H,L,V,G -
existing and planned
detector sites



- x10 better sensitivity than 1G
- aLIGO (H,L) and aVirgo(V) are being constructed. Plans for KAGRA (J) and LIGO-India (I), + GEO-HF (G)
 - target detection of anticipated NS-NS and possibly other sources after 2015.
 - extended network significantly enhances GW&MM (multi-messenger) observations

- Noise scaled network antenna vectors

$$\vec{f}_+ = \frac{F_{1+}(\theta, \phi, \psi)}{\sqrt{S_1(\omega)}, \dots, \frac{F_{K+}(\theta, \phi, \psi)}{\sqrt{S_K(\omega)}, \quad \vec{f}_\times = \frac{F_{1\times}(\theta, \phi, \psi)}{\sqrt{S_1(\omega)}, \dots, \frac{F_{K\times}(\theta, \phi, \psi)}{\sqrt{S_K(\omega)}}$$

S_k – single-sided power spectral density of detector noise

assume dominant polarization wave frame: $(\vec{f}_+(\psi) \cdot \vec{f}_\times(\psi)) = 0$

- Network response

$$\vec{h}_{\text{det}}(\omega) = [\vec{f}_+, \vec{f}_\times] \begin{bmatrix} h_+(\omega) \\ h_\times(\omega) \end{bmatrix}$$

- Network noise

$$S_{\text{net}} = \left(\sum_k S_k^{-1} \right)^{-1} \sim \frac{S_{\text{det}}}{K}$$

- Network SNR

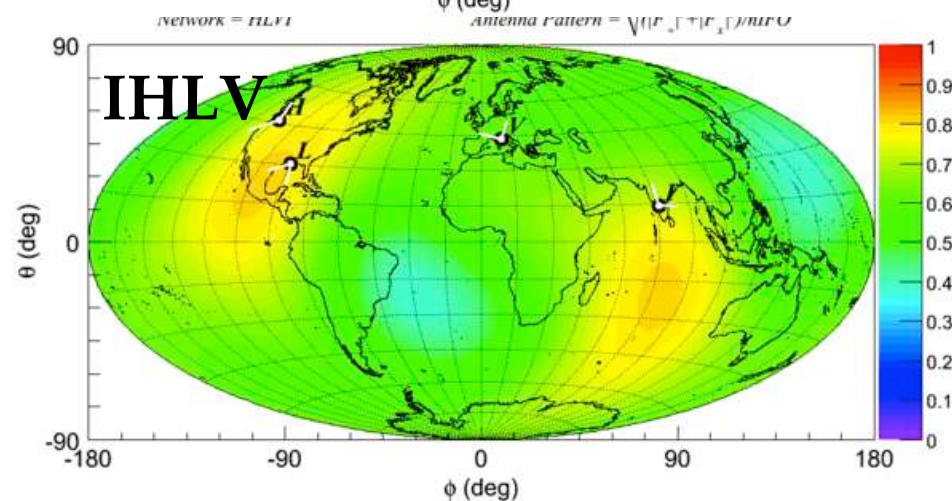
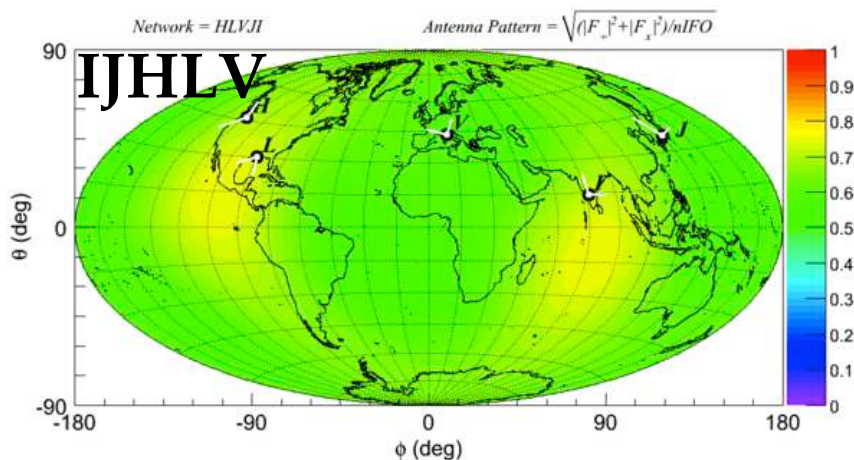
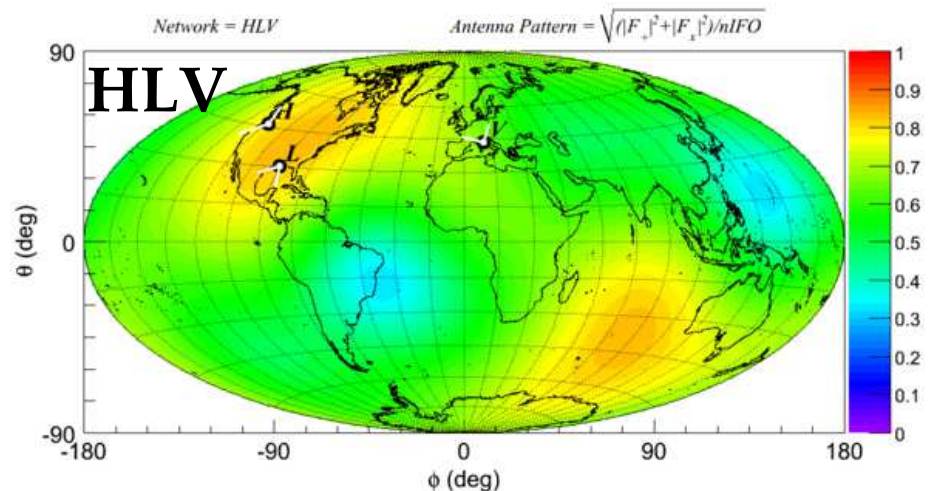
$$\rho_{\text{net}} \approx \frac{F \cdot h_{\text{rss}}}{\sqrt{S_{\text{net}}}}, \quad h_{\text{rss}} = \sqrt{\int [h_+^2(\omega) + h_\times^2(\omega)] d\omega}$$

Klimenko, et al PRD 83, 102001 (2011)
Schutz, arXiv:1102.5421(2011)

$$F = \sqrt{(|f_+|^2 + |f_\times|^2)} S_{net}$$

Antenna sensitivity w.r.t
a network of
omni-directional detectors
(100% acceptance)

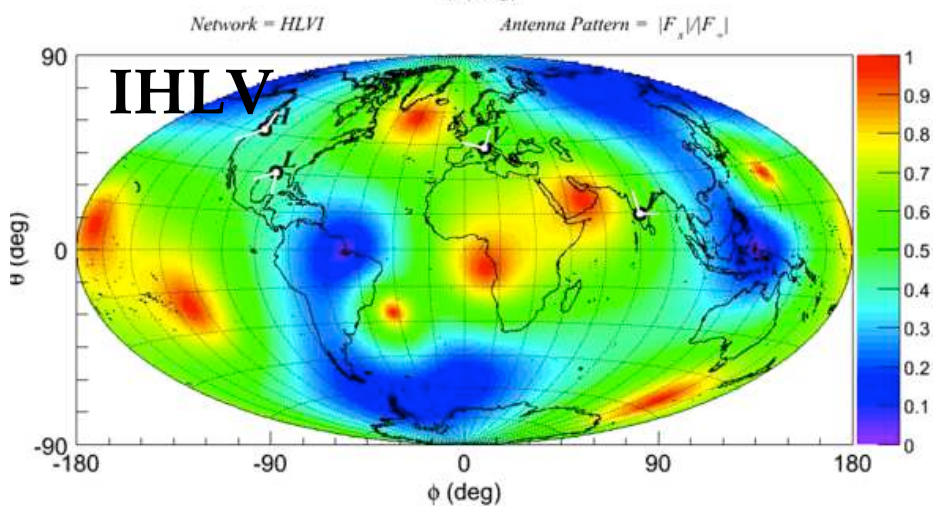
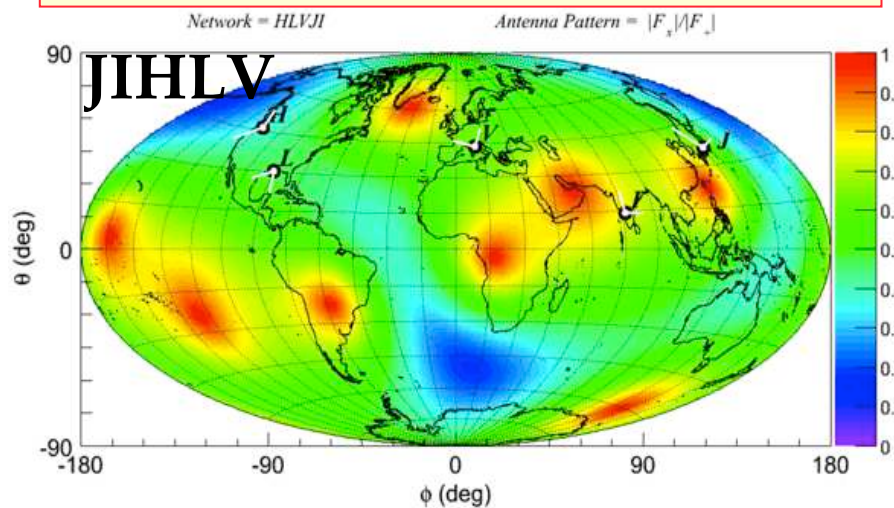
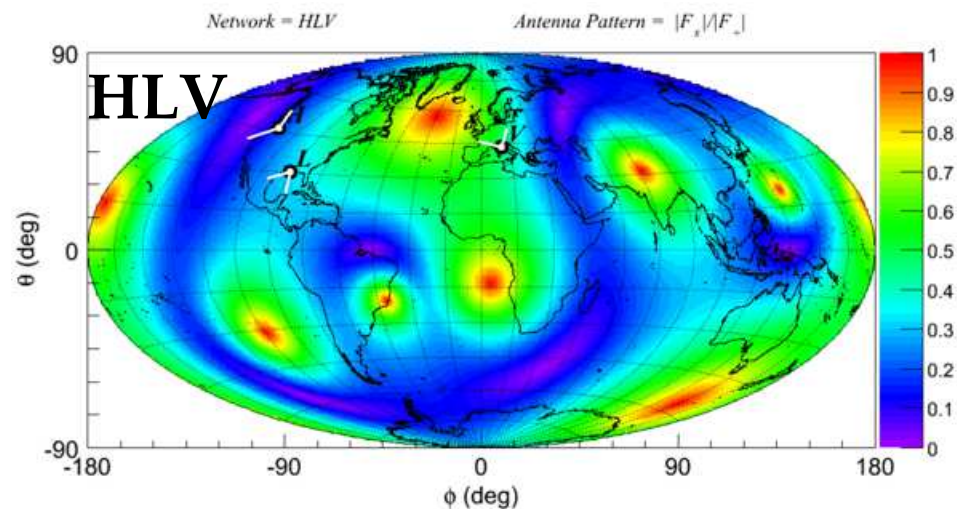
here and later for calculation of antenna
patterns we assume equal sensitivity of
all detectors – actual patterns are
frequency dependent



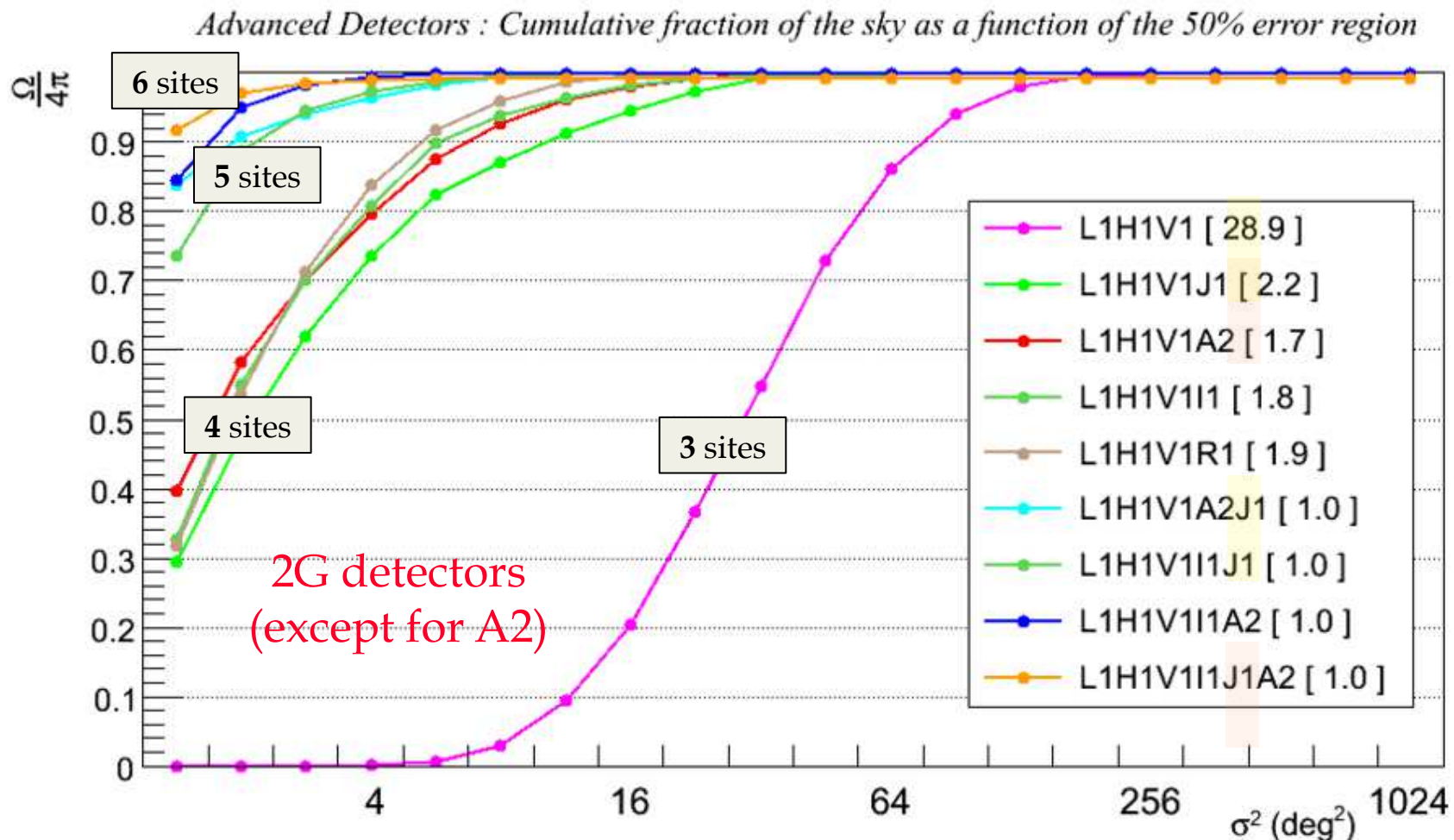
$$A = \frac{|f_{\times}|}{|f_{+}|}$$

important for reconstruction of both GW polarizations and sky localization

- for perfectly co-aligned detectors $A=0$ – detect only one GW component
- A - contribution to total network SNR from the second component

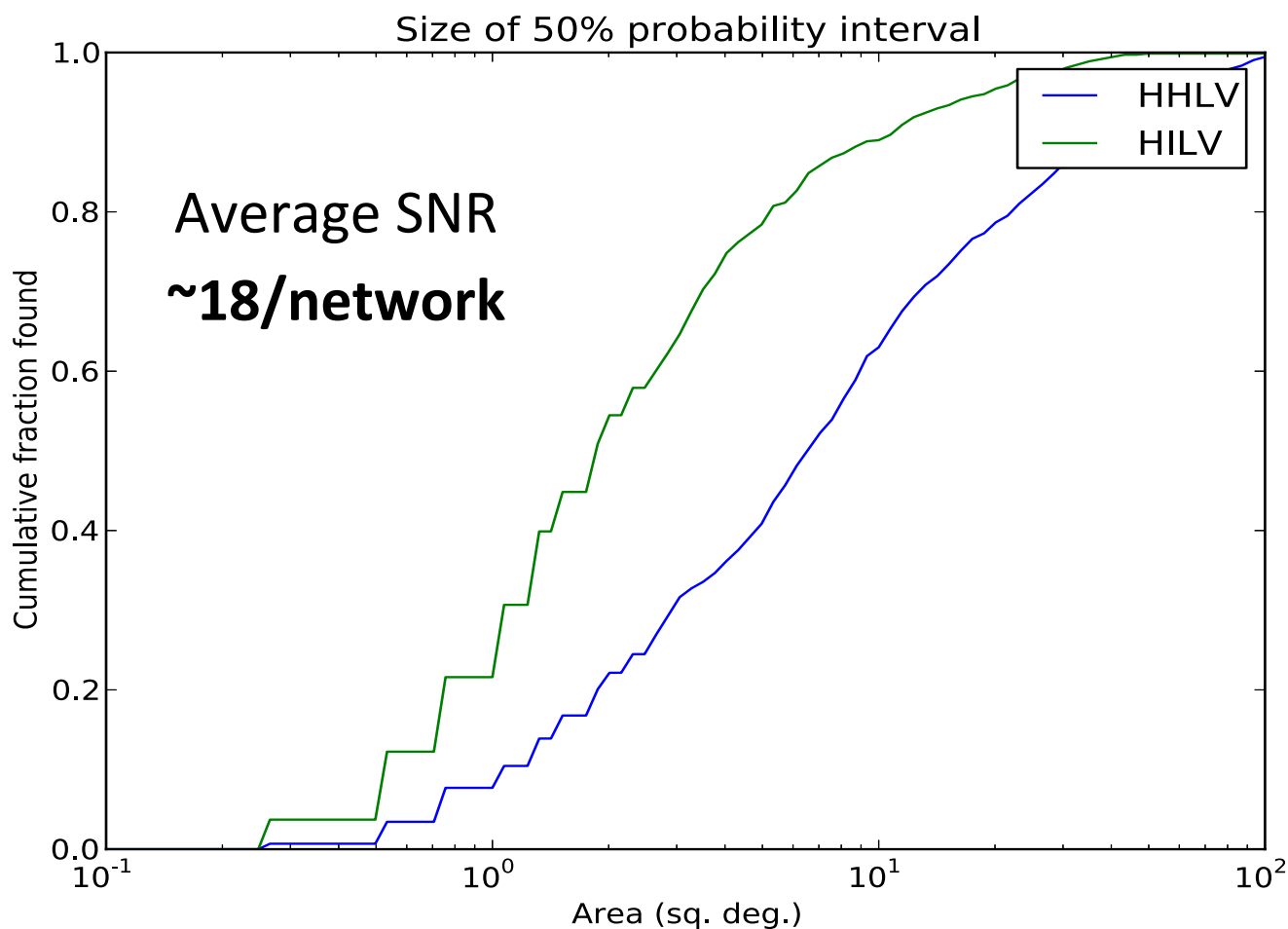


- Median error angle (50% CL, SNR_{net}<30, un-modeled sources) for reconstruction of ad-hoc signals (sine-Gaussians) in the bucket (200-300 Hz)
 - obvious observation – more sites is better



3
4
5
6

Veitch et al Phys. Rev. D 85, 104045 (2012)



- **2G sky localization is compatible with FOV of many telescopes**



Optimal networks



- **2G network reconstruction performance**
 - different detector tuning: broadband, NS-NS, HF.
 - fairly good source localization (~10 sq. degrees @90CL)
 - ✓ can be better for modeled sources
 - ✓ challenging for low frequency signals (150Hz and lower)
 - reconstruction of GW polarizations for a small fraction of sky
- **2G network is a “discovery machine” – astroGW landscape is quite uncertain**
 - may not be optimal in capturing astrophysics.

However, how far is the 2G network from optimal?



3G detectors (and beyond)



- **3G R&D has started (ET, LIGO-3G,..).**

(detection of GWs is a prerequisite for construction of 3G detectors)

- Improve high-frequency sensitivity ($\sim 1\text{kHz}$) (high power, squeezing, tuning,..)

- ✓ core-collapse SN, NS EOS, NS f-modes,..

- Extend 3G sensitivity to lower frequency (10Hz or less) (seismic super-isolation, underground/space, reduced thermal noise, Newtonian noise subtraction,..)

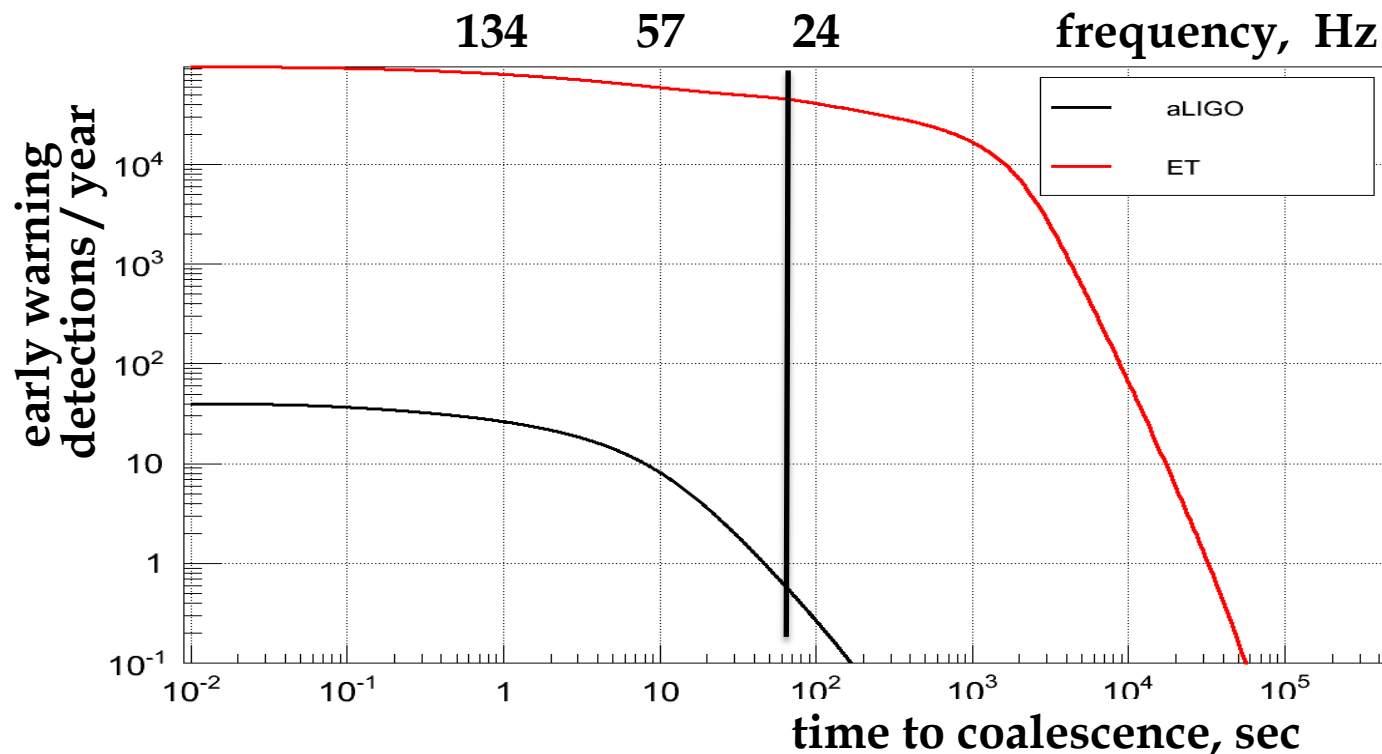
- ✓ IMBH sources (up to $10^4 M_{\odot}$)

- ✓ eccentric binary black holes

- ✓ WD binaries ($f < 1\text{Hz}$)

- ✓ NS-NS (to capture early inspiral stage $f < 30\text{Hz}$)

- To capture EM signature, localize NS-NS before merger ($T_{EM} - T_{GW} = ?$)



- 1 minute warning: sky localization in frequency band $f < 30\text{Hz}$: $\lambda/d \sim 1$
- 90% of SNR is accumulated before $f < 150\text{Hz}$ (aLIGO)
- **Apart from improved sensitivity what other upgrades are desirable for MM astronomy? More sites? More detectors?**

- Source localization can be obtained with two methods
- 1. Triangulation (fails at low frequency where most of promising GW emitters – binary inspirals – are expected)

$$\Delta\Omega_{3f} = \frac{c^2}{8\pi} \frac{1}{f^2 \rho_N^2 A_\perp} \sqrt{\frac{1}{\rho_1^2 \rho_2^2 \rho_3^2 / \rho_N^6}}, \propto \left(\frac{\lambda}{d}\right)^2, \quad d = \sqrt{A_\perp}$$

L Wen, LIGO=P070020
S. Feirhurst, NJP. 11 (2009)

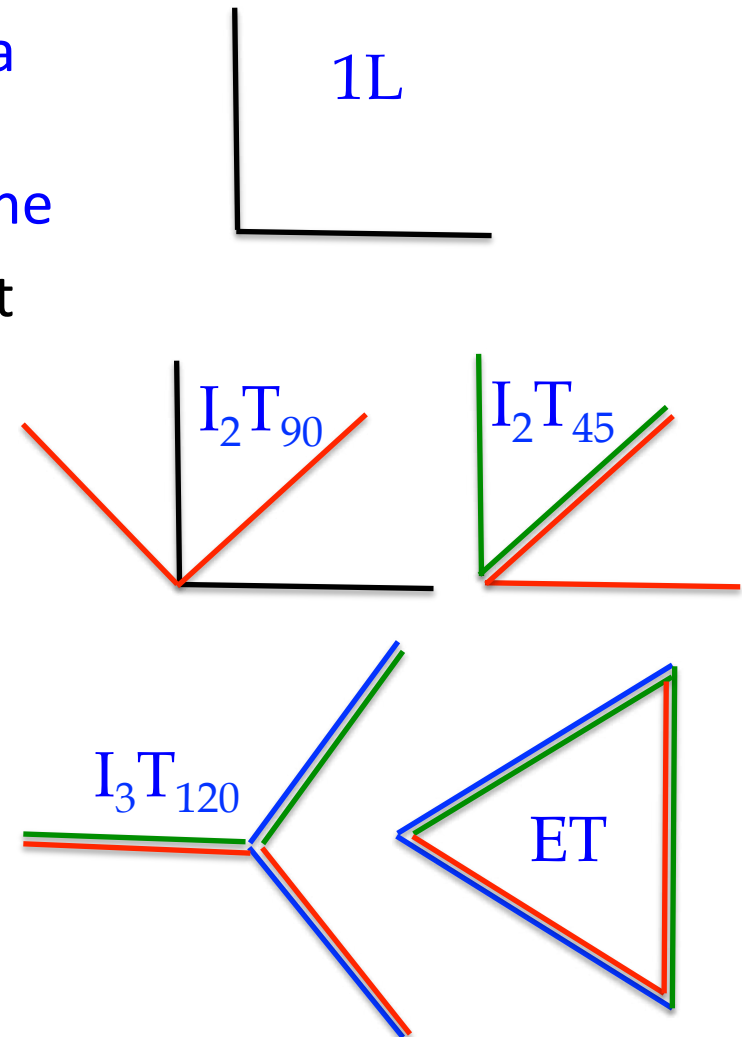
2. Network antenna coverage

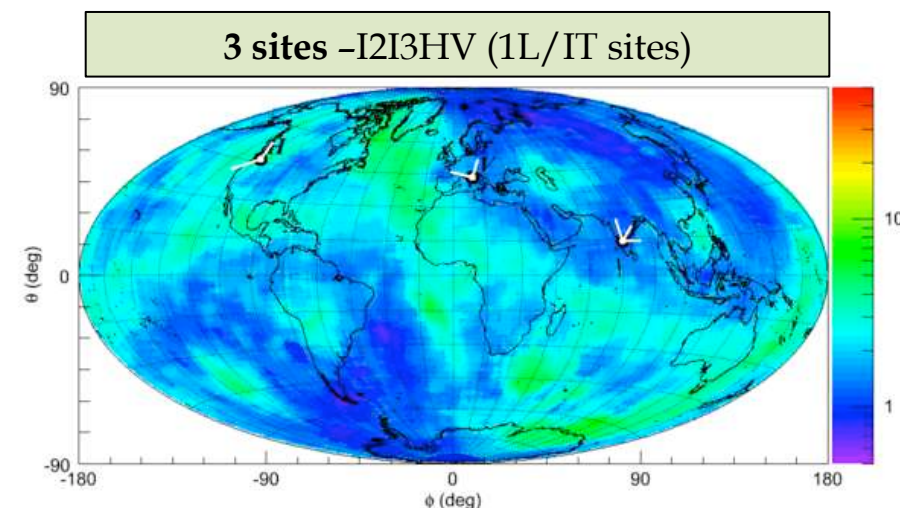
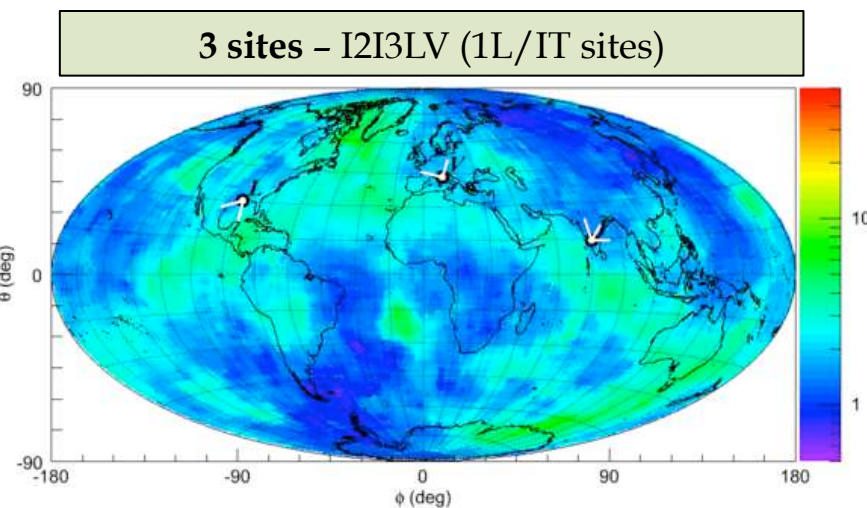
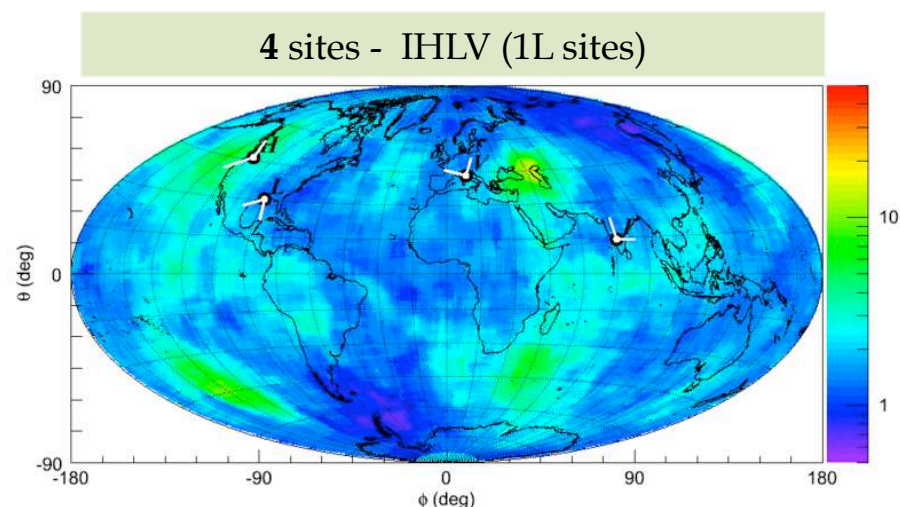
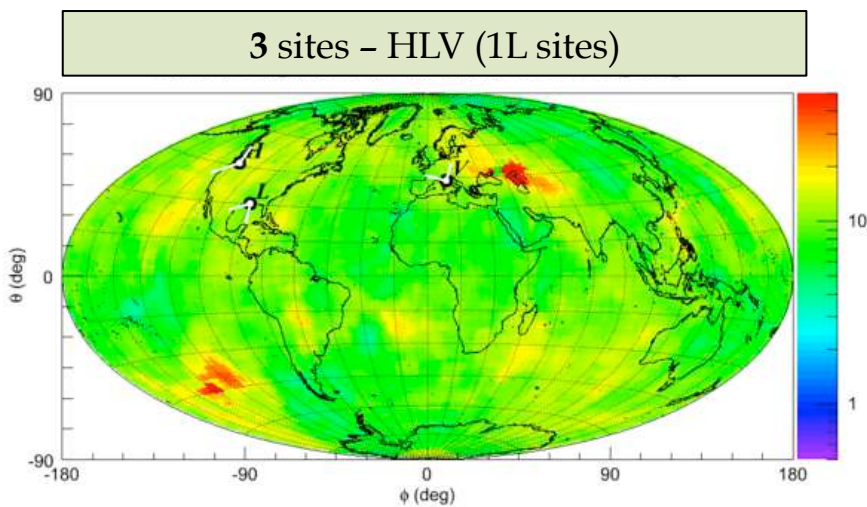
- Important for reconstruction of h_+ , h_x and hence source parameters
- Dominates localization at low frequency (not affected by diffraction limit)
- Strongly depends on number of sites, locations and also site topology (number of detectors on site and orientation of their arms)
 - ✓ How do site topology affect detection & reconstruction?
 - ✓ What are optimal and potentially upgradable site topologies
 - ✓ Does it matter at all?

How to increase polarization coverage and improve sky localization?

Use **invariant topology** where site antenna sensitivity does not depend on the global orientation of detector arms in the site plane

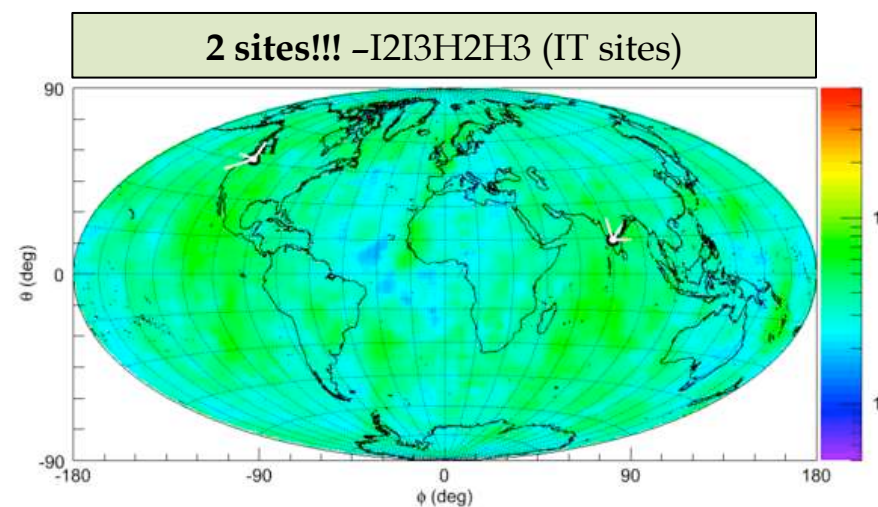
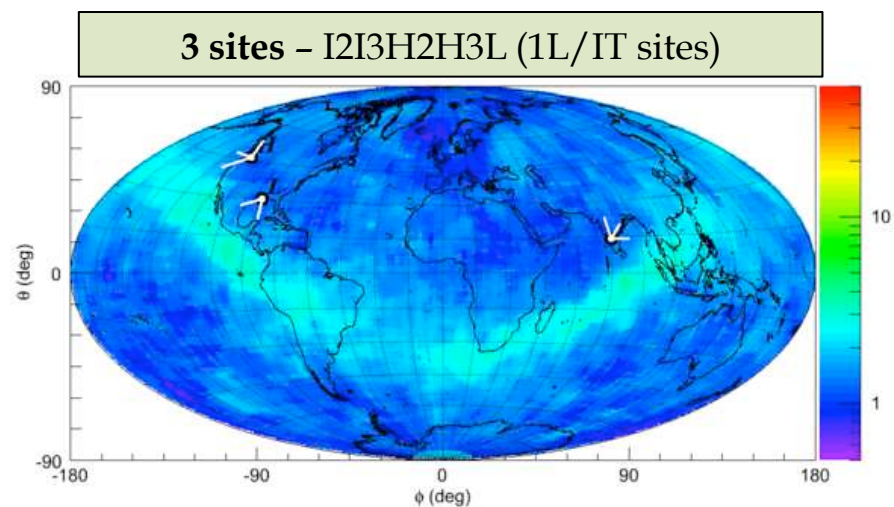
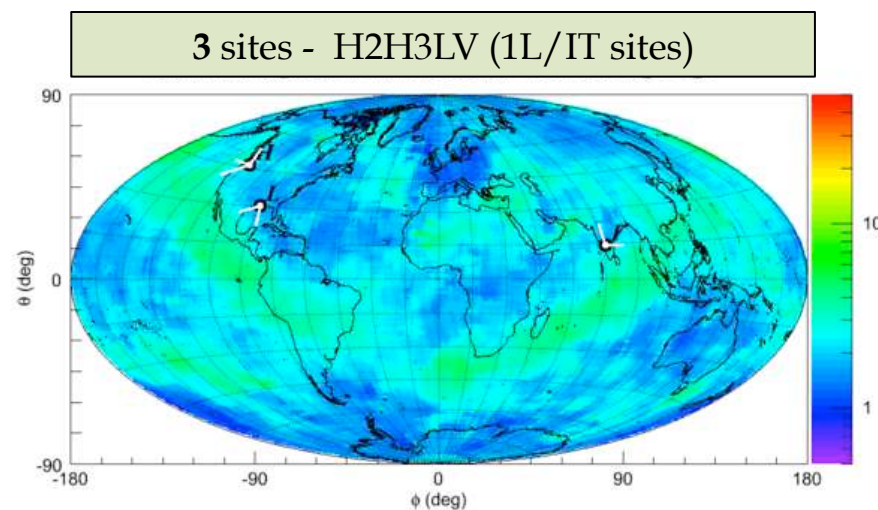
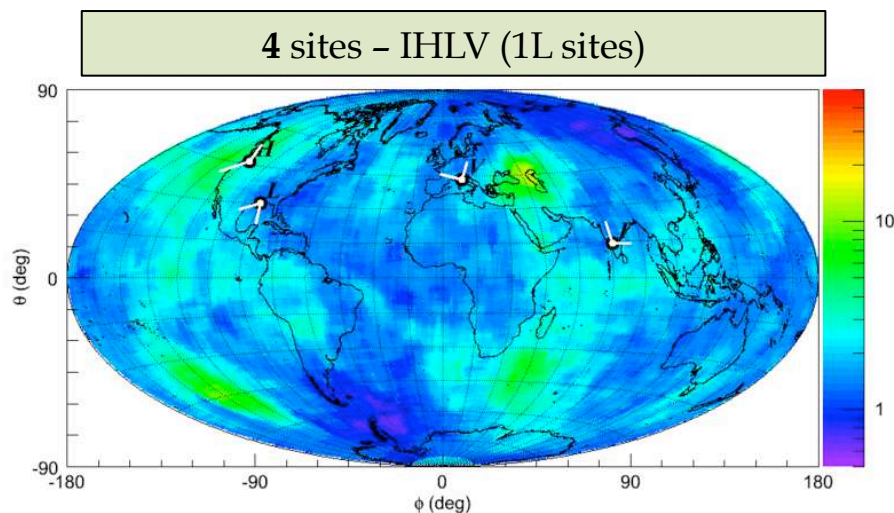
- one L-shape (1L) detector – not invariant
- Interferometric Telescopes (IT): many invariant topologies
 - 2 detectors (I_2T) - possible upgrade for L-site: build one/two more arms
 - 3 detectors (I_3T/ET)





- **IT-India** (I2&I3 with I_2T_{45} topology) detectors instead of one L-shaped detector
 - provide resolution comparable with the 4 L-site network

BIG EFFECT!!

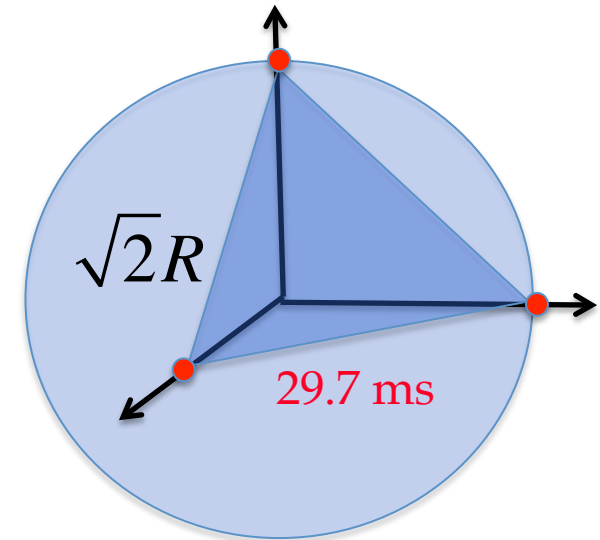


- Telescope in Hanford: $I_2T - H2\&H3$
 - excellent reconstruction with 3-site networks
 - much better than the L-shape HLV

can't ignore site topology designing future networks

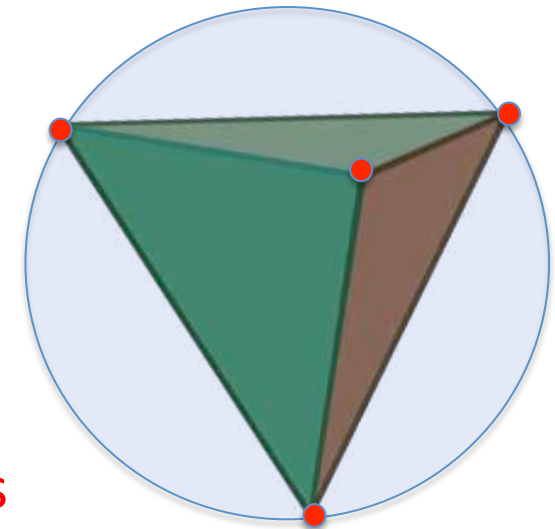
- 3-site networks

- triangulation is best for Big Circle network : $\sqrt{3}R$
- But optimal network is Cartesian: \rightarrow
- JLV&JHV very close to Cartesian

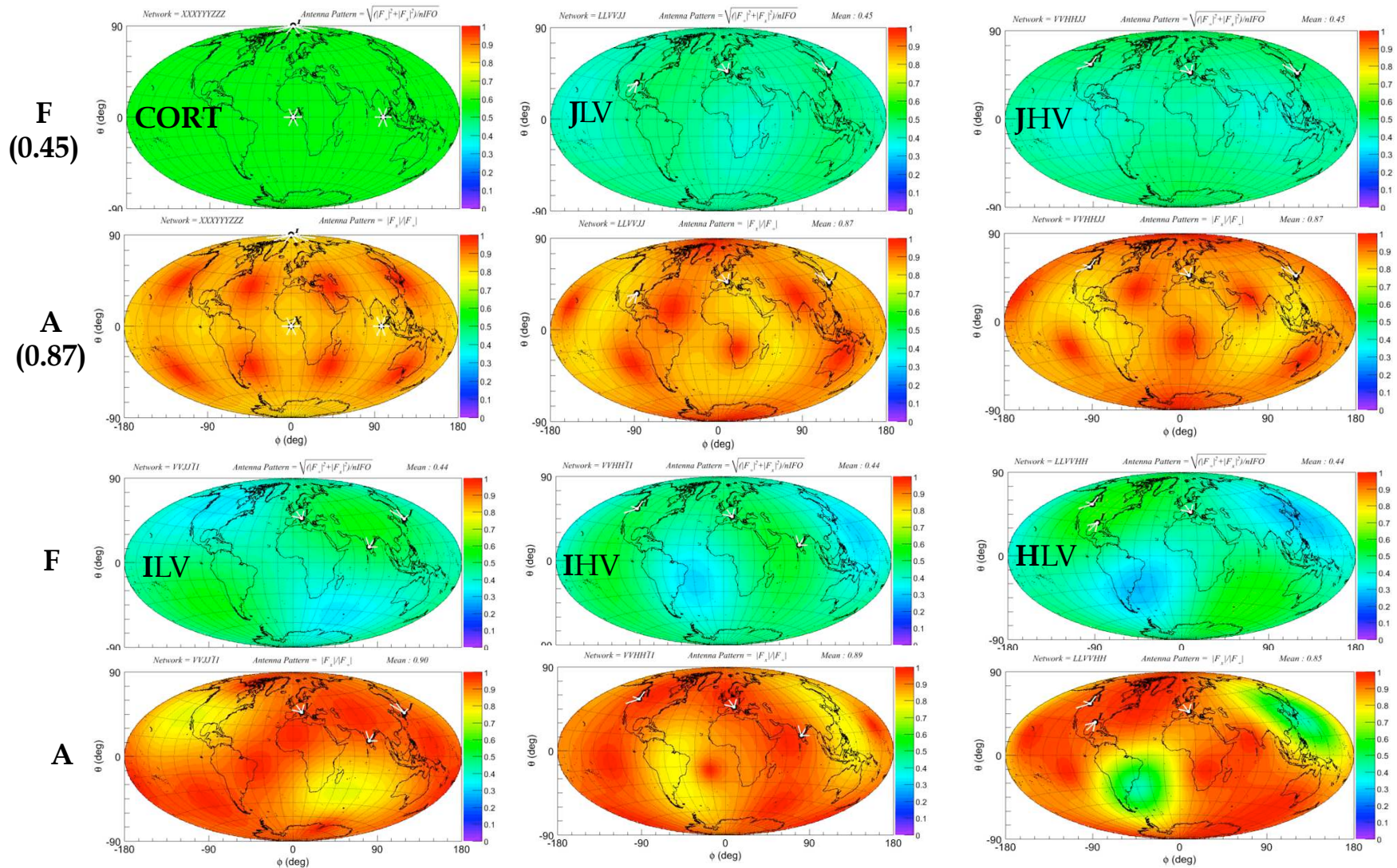


- 4-site networks

- Best triangulation and antenna coverage is obtained for tetrahedron
- Extending JLV/JHV sites, closest to tetrahedron is a site either in Australia or Argentina (excluding the most optimal location at South Pole)

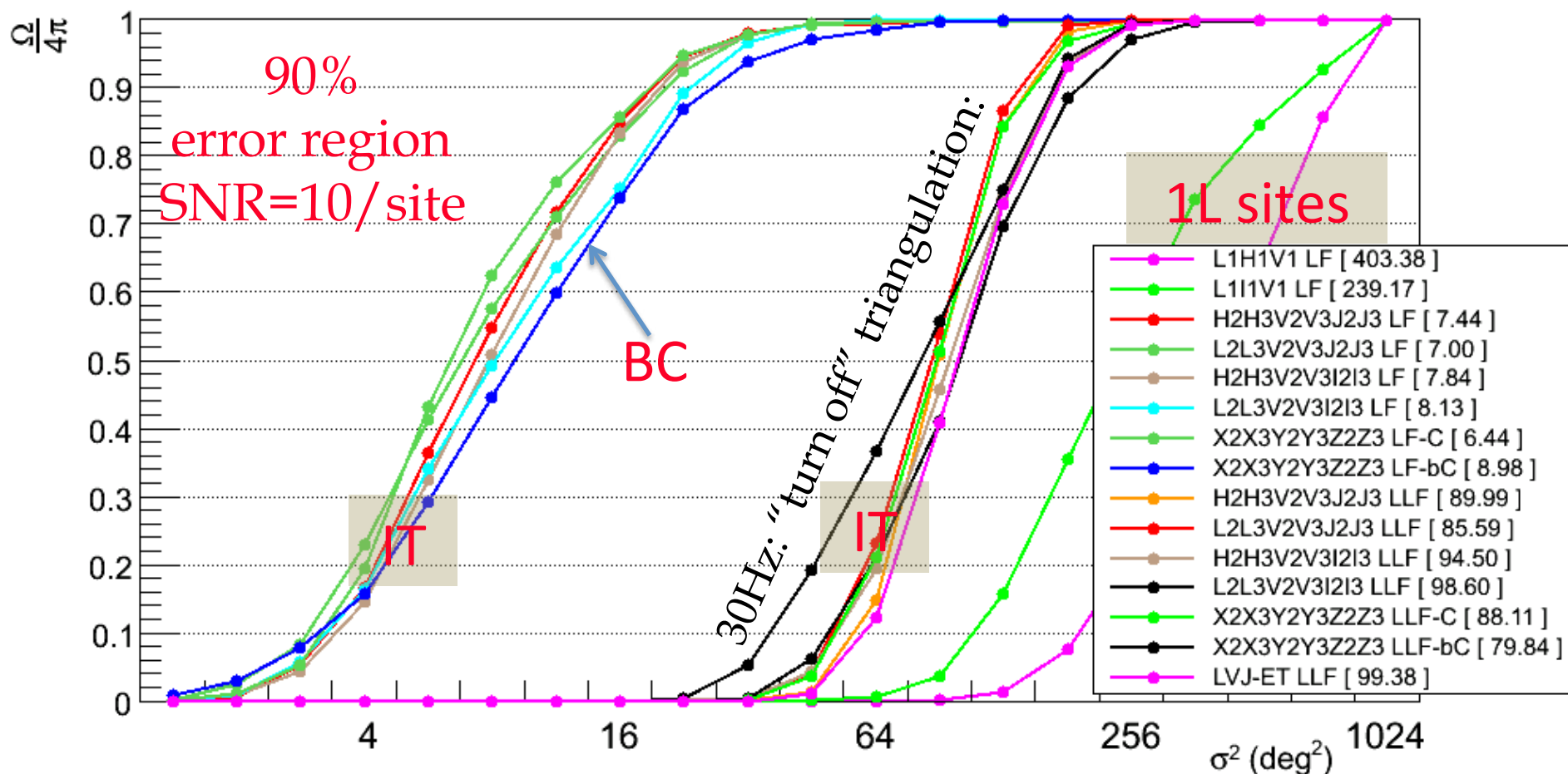


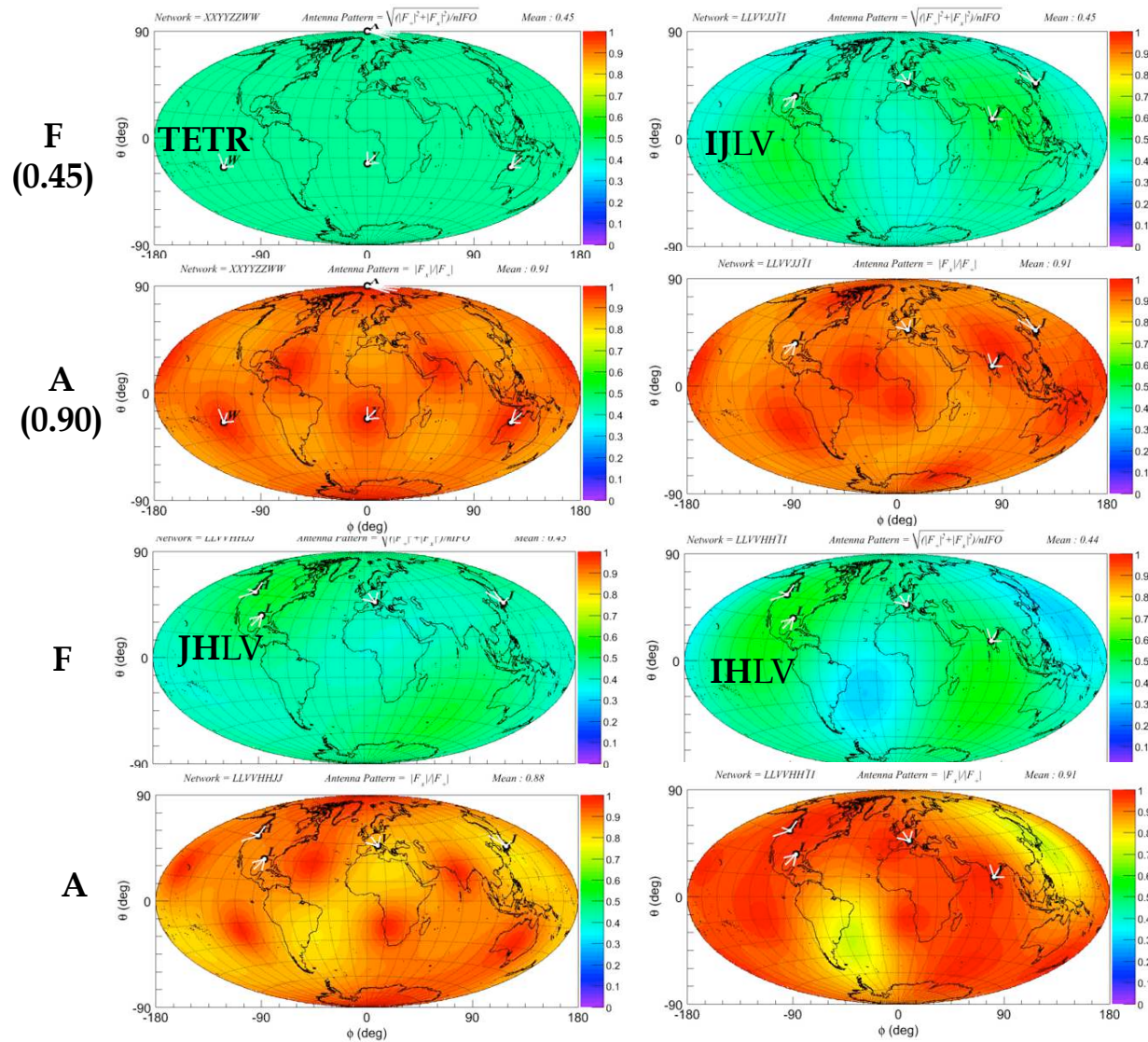
- How far are existing and planned network sites from optimal?



- JLV & JHV are close to optimal. IJH, IHV, ILV, HLV are less optimal but anyway provide much better coverage than 1L-topology networks

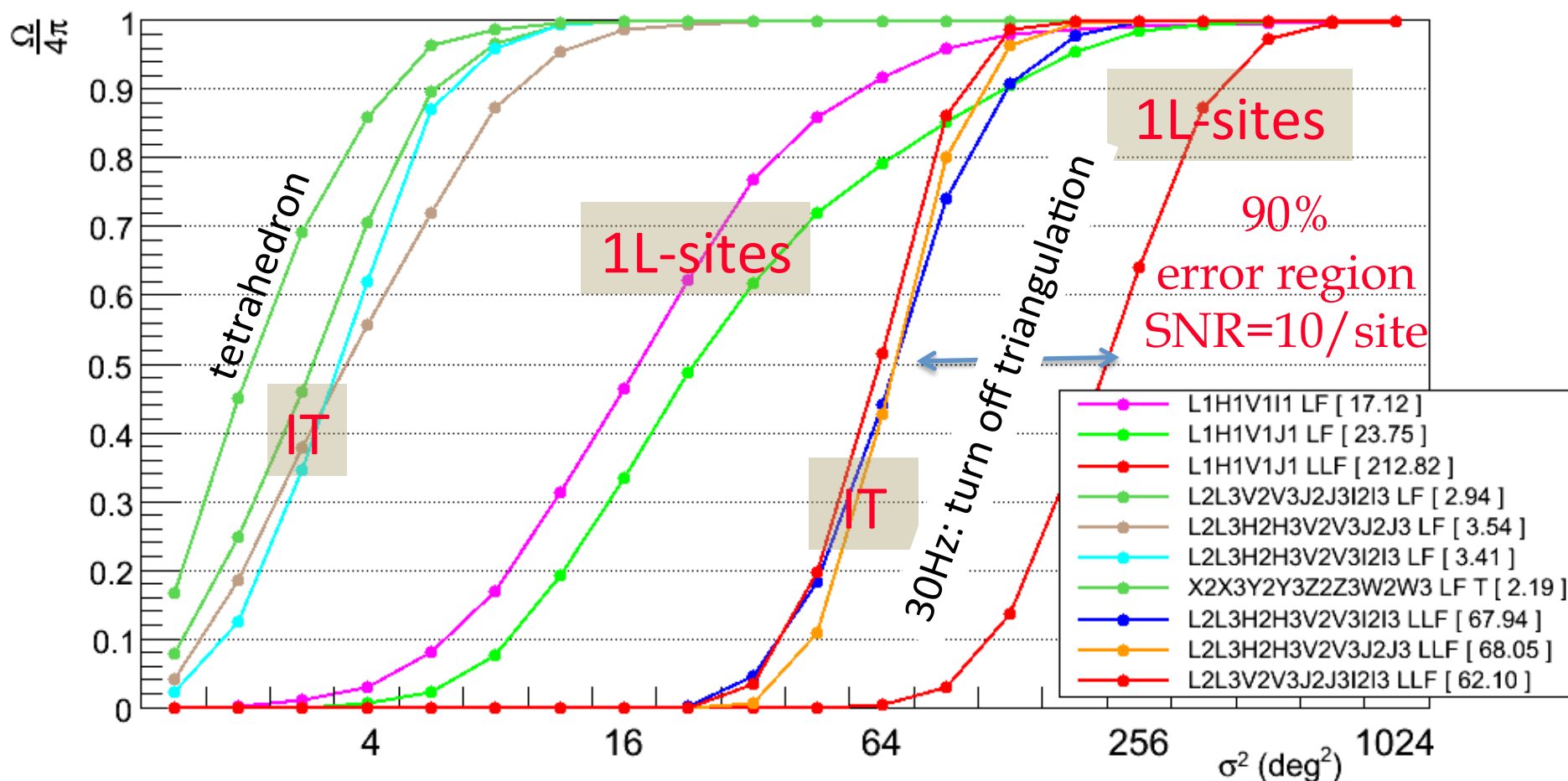
- Cartesian is better than BigCircle, which has better triangulation
- sky localization of 3 IT-site networks (including India) is close to optimal
 - >30x better than networks with 3 1L sites (same SNR 10/site)





- Excellent coverage close to tetrahedron

- Tetrahedron is optimal, but 4 IT-site networks formed with the IJHLV sites are comparable
- Both 3&4 IT-sites are much better than 4 1L sites
- decent resolution @30Hz with both 3&4 IT sites





Summary



- Existing (H,L,V) and planned (I,J) site locations are close to optimal. This network has a great potential to produce exciting science ... and a lot of room for improvement
- Localization of GW sources benefits (particularly at low frequency) from full coverage of source polarizations
- Invariant topology significantly improves reconstruction and could be a viable upgrade for 2G network after first detections:
 - upgrade of site topology is as important as building new sites
 - may not be possible for some existing sites due to hard constraints: geography, buildings, ... A mixture of different site topologies can be used: more IT sites – better.